

# *Advanced 3D Graphics*

*... where Computer Graphics meets AI*



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# *Advanced 3D Graphics*

## *Focus : where Computer Graphics meets AI*

### *Part 1. “Creative AI” – Intelligent systems helping users in creative tasks*

1. Expressive 3D modeling : smart geometry controlled by gestures
  - Shape representations for constructive modeling
  - Sculpting, sketching, transfer metaphors
2. Extension to virtual worlds
  - Modeling and animating natural scenes
  - Expressive creation & control of animated scenes

### *Part 2. Autonomous characters – animation & control*

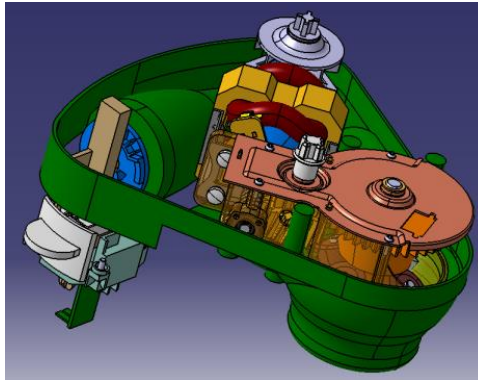
3. Motion planning for characters and crowds
4. Animating and controlling individual characters



# *3D Computer Graphics*

## *See and touch imaginary worlds ?*

@Grenoble-INP avec Lyon 1, Inria



- Design, refine and fabricate imaginary 3D shapes
- Give life and explore animated virtual worlds...

*Playful dimension... and a wonderful tool!*



# Digital creation in 3D Computer Graphics

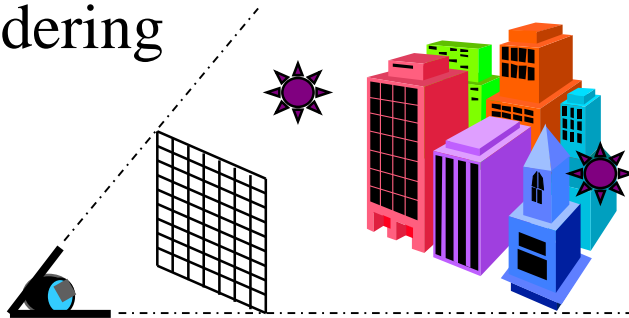
*How can we help the  
user create them?*

Not “image processing”, not “imaging”

– Input: mathematical models... Output: images!

3 steps

1. Geometric modeling
2. Animation
3. Rendering



# *Advanced 3D Graphics*

## *Focus : where Computer Graphics meets AI*

*Part 1. “Creative AI” – Intelligent systems helping users in creative tasks*

1. **Expressive 3D modeling** : smart geometry controlled by gestures
  - Section 1: Shape representations for constructive modeling
  - Section 2: Sculpting, sketching, & transfer metaphors
2. Extension to virtual worlds
  - Modeling and animating natural scenes
  - Expressive creation & control of animated scenes

*Part 2. Autonomous characters – animation & control*

3. Motion planning for characters and crowds
4. Animating and controlling individual characters



# *Part 1, Chapter 1: Expressive modeling*

## *Section 1: Shape representations*

### **Objectives**

- Creating new shapes (no reconstruction)
  - User control (no automatic generation)
- *Interactive 3D modeling*



### **In this section**

- Notion of « constructive modeling »
- Reminder on different shape representations
- Recent advances in **implicit modeling**





- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

## *3D Shapes : a few definitions*

*Shape* : Geometric Structure in a 3D space

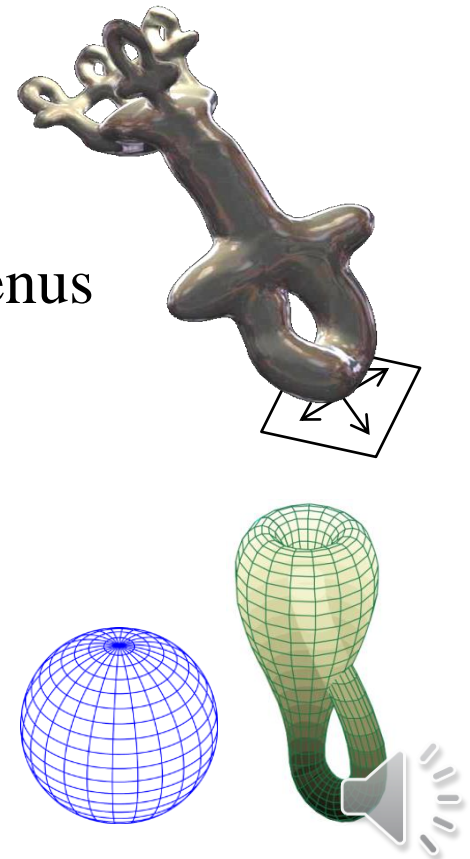
- 1D (curve), 2D (surface), 3D (volume)
- Any combination of the above!

*Free form* shape : arbitrary geometry and topological genus

*Smooth* shape:

- $C^1$  : tangent continuity
- $C^2$  : curvature continuity

*3D shapes: Volume vs. Border Representation (B-Rep)*



# 3D shapes

## *Machines view-point*

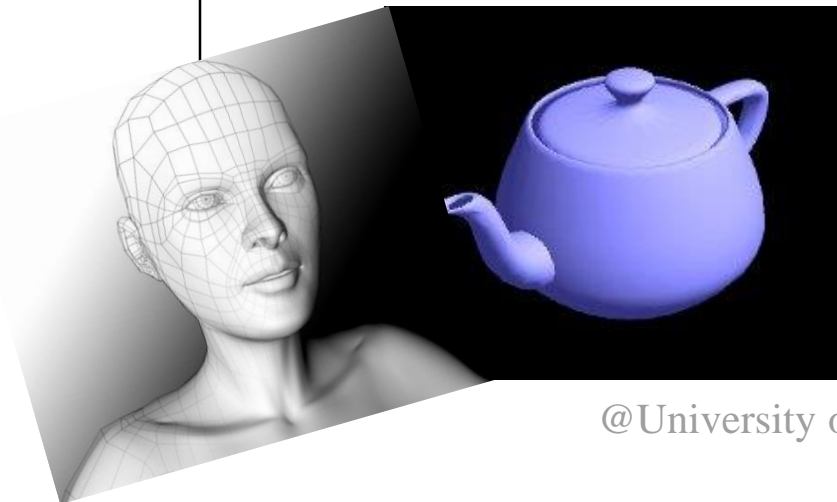
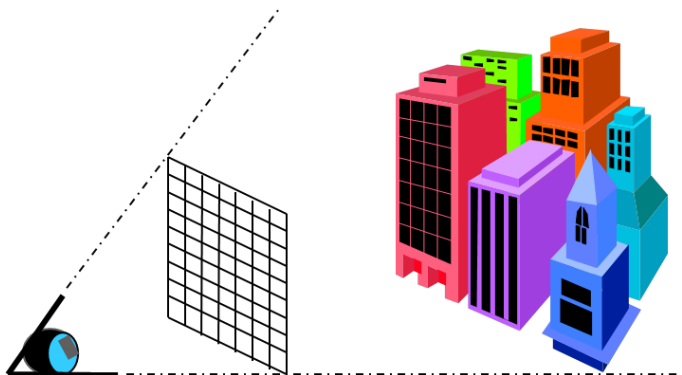
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## *Human view-point*

- Mathematical model
  - Enumerated (list of faces)
  - Equation to compute them
- Rendering : projection of faces

[M. Leyton – cognitive sciences]

- Shape = assembly of parts
- Part = deformation of a symmetrical « primitive shape »



[A generative theory of shapes. M. Leyton, Springer]

@University of Utah, 1982





# 3D shapes

## *Machines view-point*

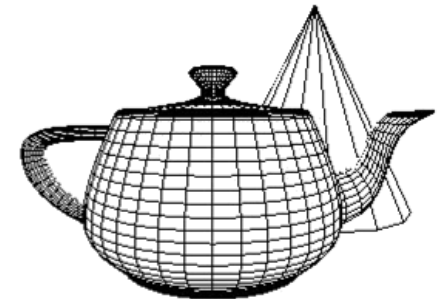
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## *Human view-point*

- Mathematical model
  - Enumerated (list of faces)
  - Equation to compute them
- **Specify degrees of freedom**
  - Give the list of faces
  - or parameter values

**Wins in the end!**

- Shape = assembly of parts
- Part = deformation of a symmetrical « primitive shape »
- **« constructive » modeling**
  - = series of operations :
    - Create
    - Deform
    - Assemble



*Source of misunderstanding!*

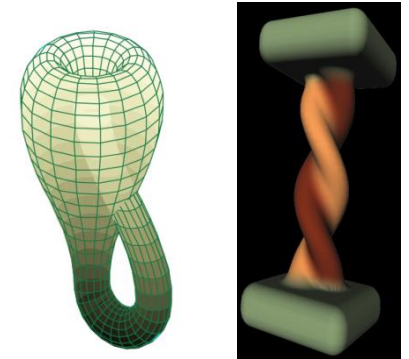


- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

## *Constructive modeling*

### *The needs*

1. Being able to create free form shapes
2. Remaining in the space of « valid shapes »
  - No Klein bottle
  - Avoid self-intersections
3. Progressive modeling and refinement
4. Real-time display
  - Whatever the duration of the modeling session



→ *Choice of an adapted representation ?*



- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

## *Discrete Representations*

### **Enumerations**

- points 0D, segments 1D
- faces 2D (*meshes* if connectivity info)
- voxels 3D : volumes



### **Non-smooth representations**

- Well suited to automatic creation
- Not adapted to manual creation

(Except as a game!)

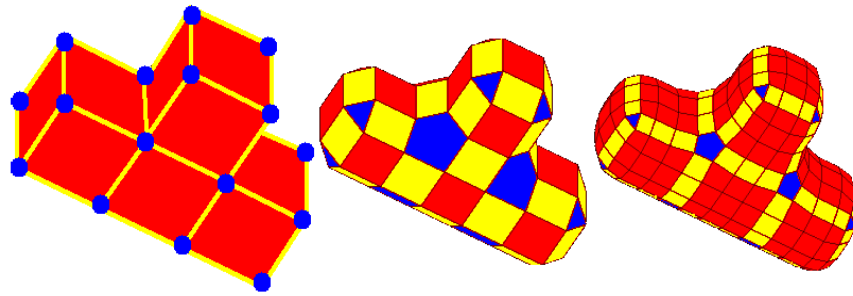
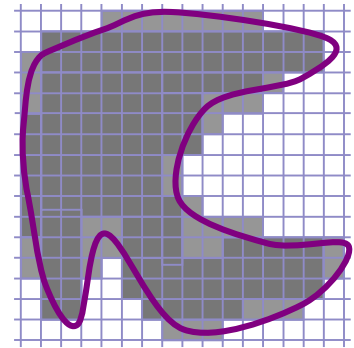


- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

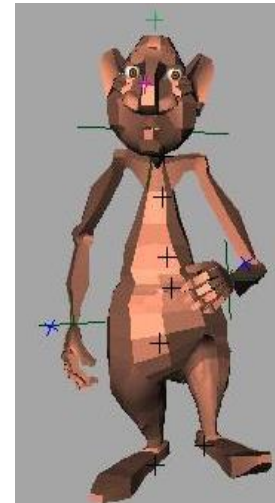
## *Algorithmic representations*

### **Discrete representation + automatic smoothing**

- *Voxels* : Interpolate a scalar density in a grid
  - Display the 0.5 iso-surface
- *Mesh* : Subdivision surfaces
  - Difficulty : controlling the limit shape



Recursively « cut corners »



- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

## *Continuous representations*

*Shape (curve, surface, volume) defined by an equation*

- **Parametric** vs **implicit formulation**

*Exemple : Sphere of radius  $r$*

Parametric surface

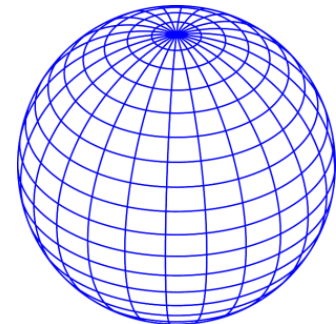
$$S(u,v) = (r \sin(u)\cos(v), r \sin(u)\sin(v), r \cos(u))$$
$$u \in [0, \pi], v \in [0, 2\pi]$$

Implicit surface

$$I = \{P \in \mathbb{R}^3 / x^2 + y^2 + z^2 = r^2\}$$

Implicit volume

$$V = \{P \in \mathbb{R}^3 / x^2 + y^2 + z^2 \leq r^2\}$$



- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

# *Constructive Modeling*

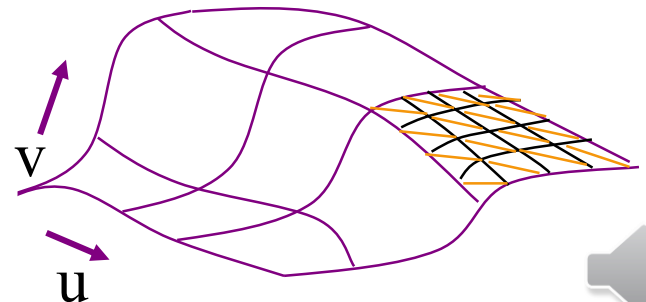
## *Choice of representation ?*

### **Advantages of continuous representations**

- Less parameters to define (ex sphere : radius, center)
- A smooth shape remains smooth at any scale
  - can be converted into different discrete representations

**Ex: Parametric surface**  $S(u, v) = (S_x(u, v), S_y(u, v), S_z(u, v))$

- Compute a grid of sample points
- Triangulate it (planar faces)





- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

# *Constructive Modeling*

## *Choosing a representation ?*

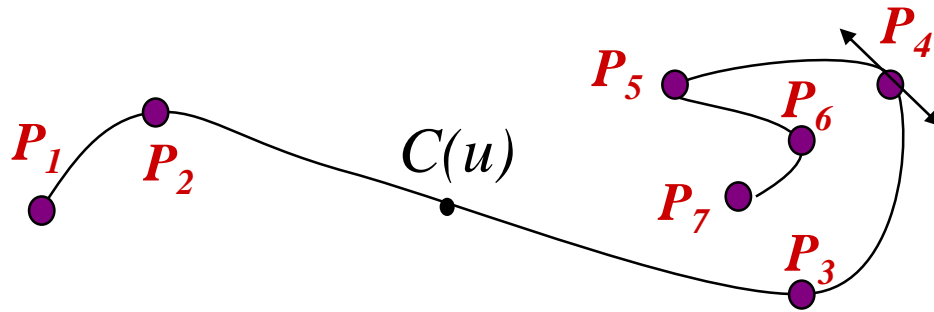
### Constructive modeling loop

1. Create primitive shapes
2. Deform – should be intuitive, local or global
3. Assemble – Seamless if possible



Can this be done with parametric surfaces ?





# *Parametric modeling*

## *Spline curves*

### **Creation**

- List of « control points »  $P_i$
- To be interpolated or approximated :  $C(u) = \sum F_i(u) P_i$

### **Deformation**

- Need for local control!
- $F_i$  low degree polynomials (degree 3), compact support

### **Assembly**

- $C^1$  or  $C^2$  at joints



- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

## Interpolation curve “Cardinal Spline”

$C^1$  at joints

$$C_i(0) = P_i$$

$$C_i(1) = P_{i+1}$$

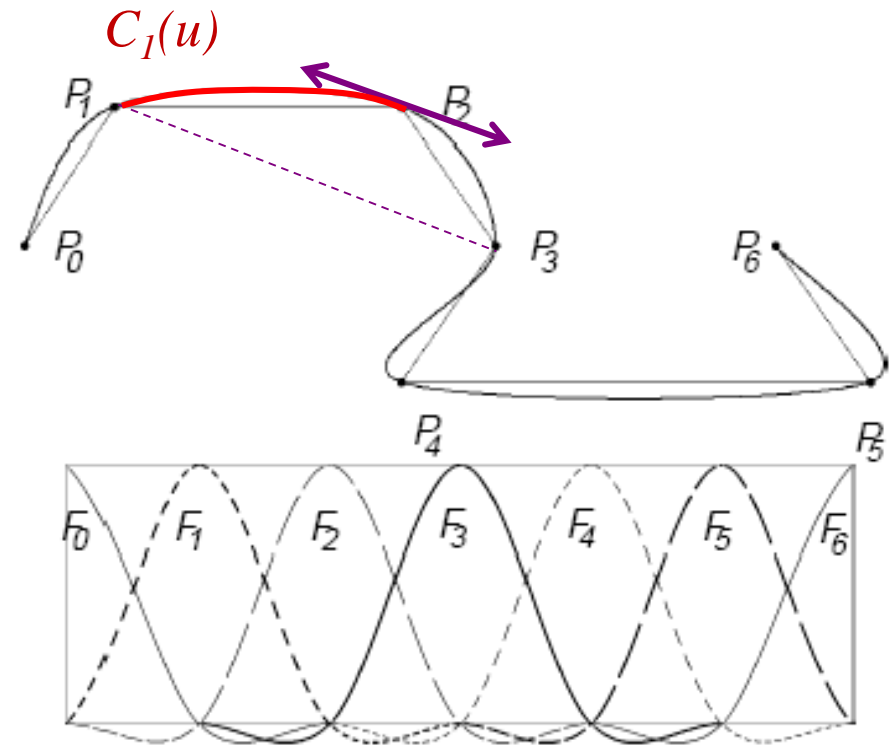
$$C'_i(0) = k ( P_{i+1} - P_{i-1} )$$

$$C'_i(1) = k ( P_{i+2} - P_i )$$

$$C_i(u) = \sum F_i(u) P_i$$

Single solution with  $F_i(u)$  of degree 3

- Local control of order 4
- $F_i(u)$  not always positive  
 $C(u)$  goes outside of the convex hull



- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

## *Approximation curve Uniform cubic B-spline*

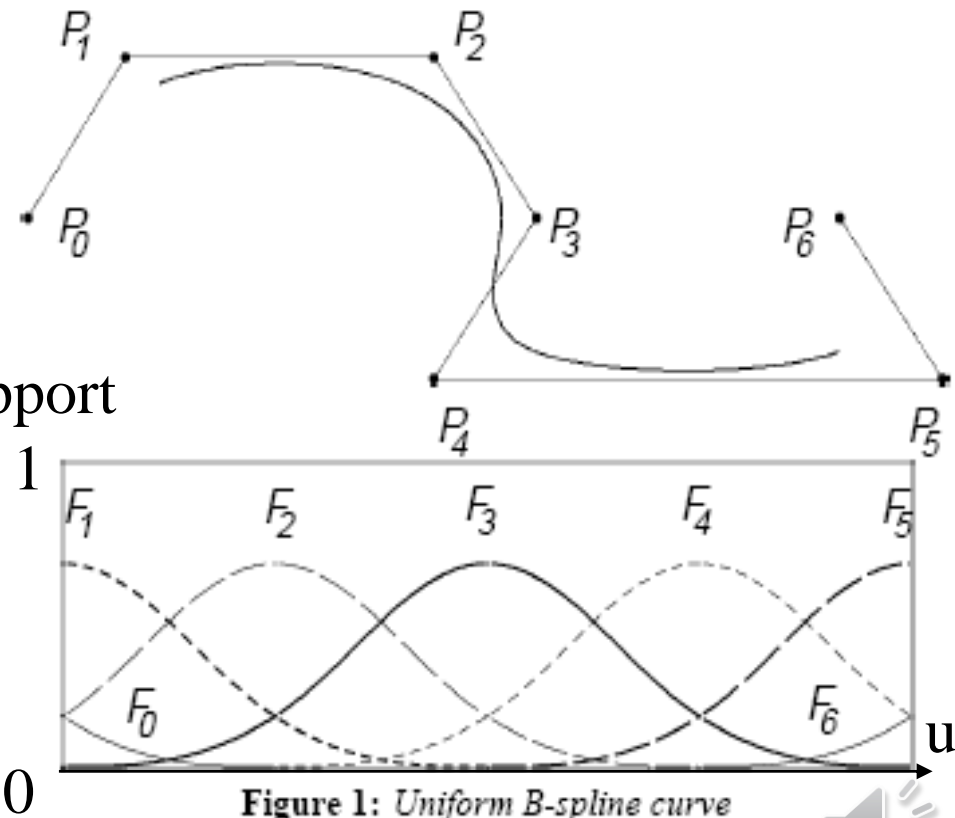
$C^2$  continuity with  $F_i$  local, of  $d^03$  ?

Curve segment defined by:

- $F_i$  built from 4  $d^03$  polynomials
- Local control of order 4
- $F_i$  continuously vanishes outside support
- Convex hull
- Regularizing curve

$$C_i(u) = \sum F_i(u) P_i$$

For all  $u$ ,  $F_i(u) \geq 0$ ,  $\sum F_i(u) = 1$



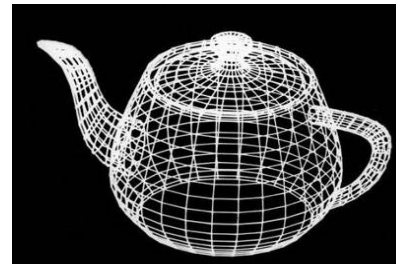
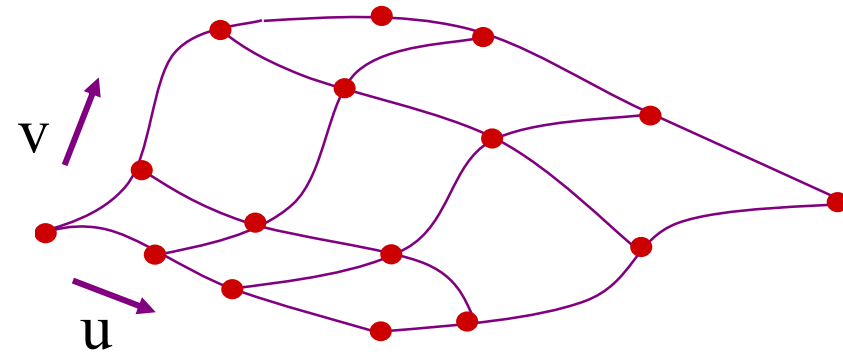
- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

## *Parametric Modeling Spline surface*

- Product of spline curves in  $u$  and  $v$

$$S_{i,j}(\mathbf{u}, \mathbf{v}) = \sum F_i(\mathbf{u}) F_j(\mathbf{v}) P_{ij}$$

- Need of a *grid* of control points
- How can we create complex shapes?



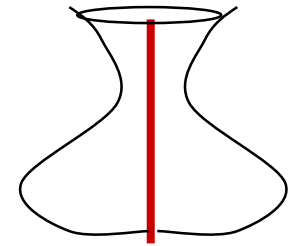
- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

## *Parametric modeling*

### *Spline surfaces: Creation*

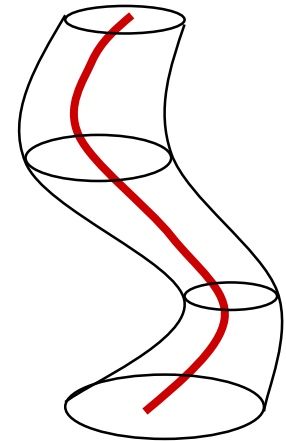
- **Surfaces of revolution**

- Rotate a planar curve around an axis



- **Extrusion**

- A skeleton curve
- A section swept along the skeleton
- A profile curve giving the scaling factor



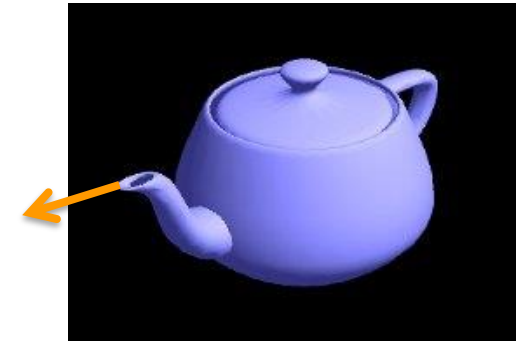


- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

## *Parametric modeling*

### *Spline surfaces: Deformation*

- **Local deformation**
  - Move control points



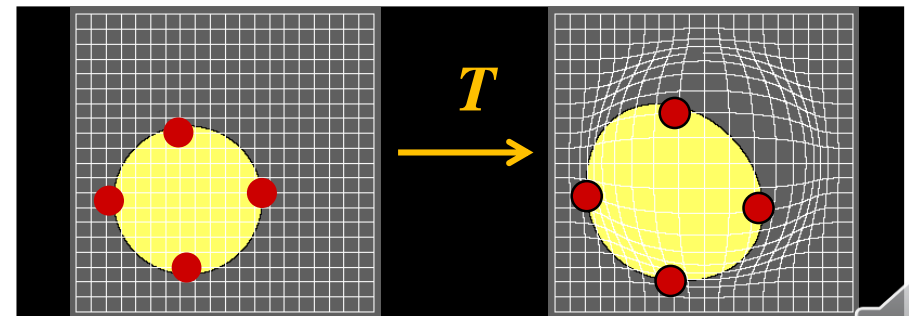
- **Global deformation?**

Use a « space deformation »  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$

Control points move

The surface deforms

*(See part on « sculpture »)*

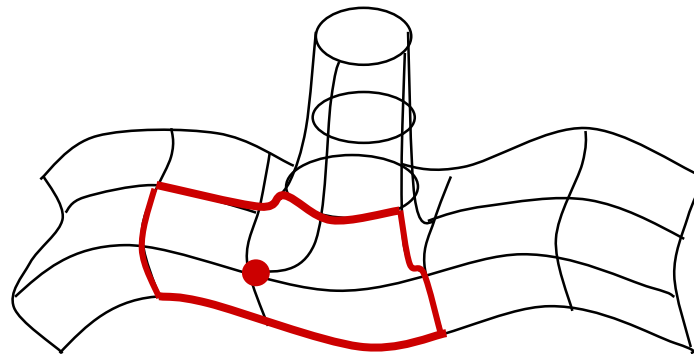
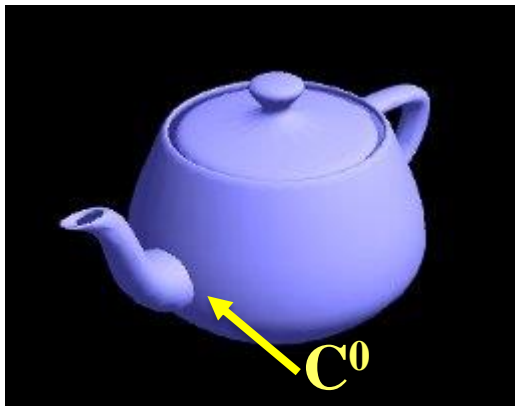
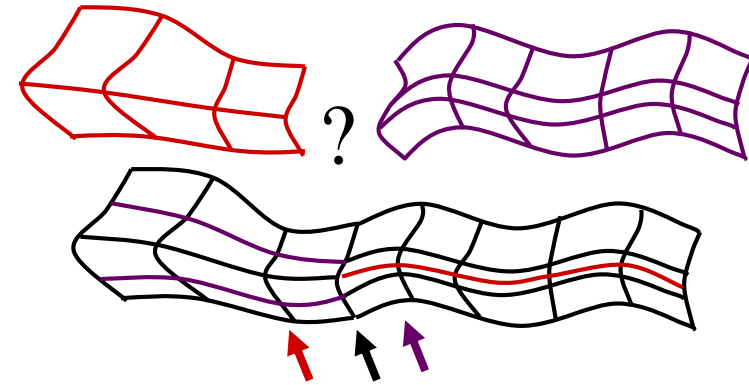


- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

## *Parametric modeling*

### *Spline surface: Assembly*

- *Along borders... OK*
  - Same number of patches needed
  - 3 common rows of control points
- *Handles, branchings?*  
Very difficult!



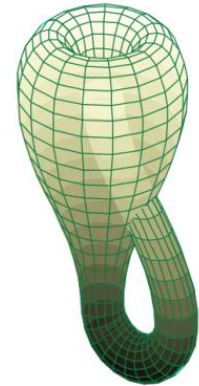
Rational S-patch [Loop90]

- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

## *Parametric surfaces*

### *Limitations*

- B-Rep only
  - No constraint against **incorrect shapes** (eg. Klein bottle...)
- **Hard to model**
  - Arbitrary topological genus
  - Smooth branchings



- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

## *Continuous representations*

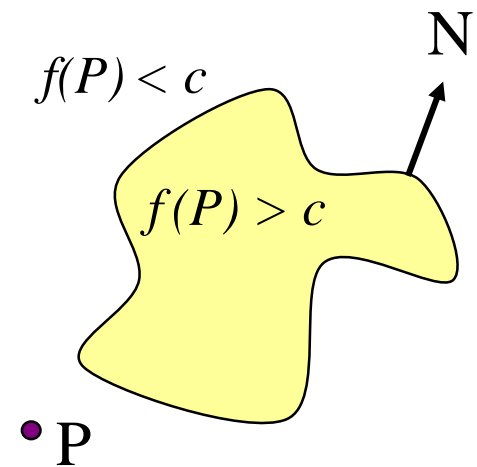
### *Implicit surfaces*

$$I = \{ P \mid f(P) = c \} \quad f : \mathbb{R}^3 \rightarrow \mathbb{R} \text{ scalar field}$$

( ex sphere :  $f(P) = x^2+y^2+z^2$ ,  $c = r^2$  )

*Hyp*:  $I$  separates space into two parts - one of finite size

- Inside volume  $f(P) > c$
- Surface normal  $N = - \nabla f$
- $f$  et  $I$  have the same degree of continuity!
- Difficult to list surface points...  
but « inside / outside » test (  $f(P) > c$  ? )

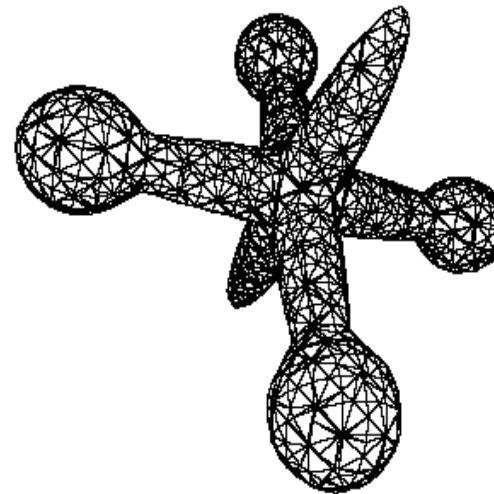
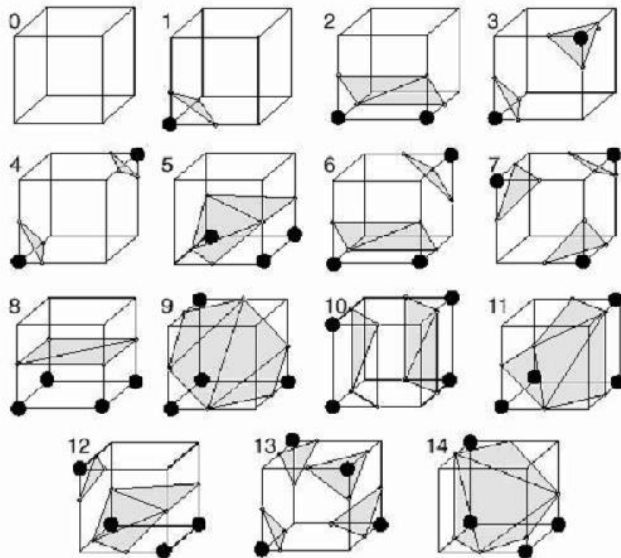
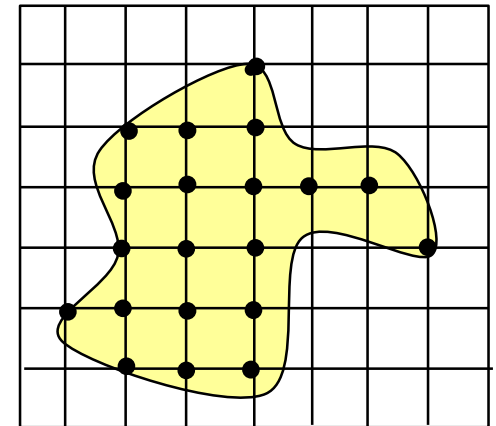


- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

# *Implicit surfaces*

## *Sampling for display*

- « **Marching cubes** » method [Lorensen 1991]
  - Inside/outside classification of grid points:  $f(P) \geq c \rightarrow black$
  - Extract cubes that cut the surface
  - Triangulate their intersection with the surface



- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

# *Constructive modeling*

## *Choosing a representation?*

### Constructive modeling loop

1. Create simple shapes
2. Deform them – should be intuitive
3. Assemble them – seamlessly if possible



Attempt with implicit surfaces ?





- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

# *Implicit surfaces*

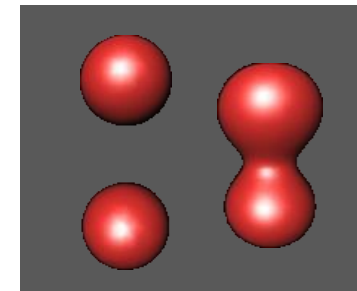
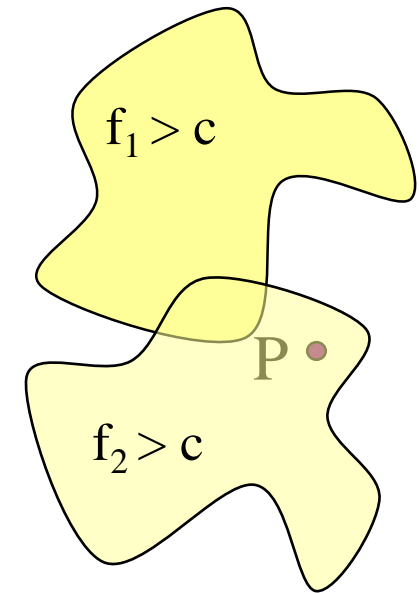
## *Assembling*

Given  $I_1 = \{ P / f_1(P) = c \}$ ,  $I_2 = \{ P / f_2(P) = c \}$   
 $f_1$  and  $f_2$  of class at least  $C^1$

**Assembling** : compute  $I = \{ P / f(P) = c \}$

- $f = \max(f_1, f_2) \rightarrow$  **Union**
- $f = \min(f_1, f_2) \rightarrow$  **Intersection**
- $f = f_1 + f_2 \rightarrow$  « **Blending** »

Preserves the degree of continuity!



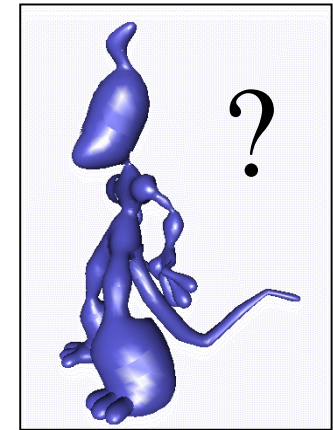
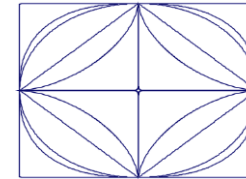
- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

# Implicit surfaces Creation ?

- Use of an equation quite limited...

Spheres :  $f(P) = x^2 + y^2 + z^2 = r^2$

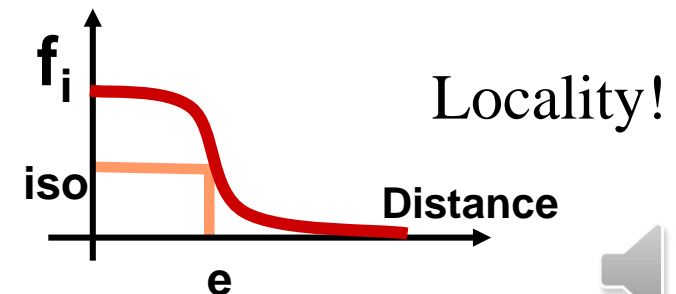
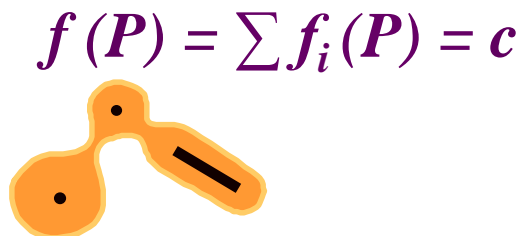
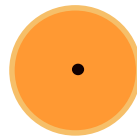
Super-ellipsoids :  $f(P) = \frac{x^n}{a^n} + \frac{y^n}{b^n} + \frac{z^n}{c^n} = 1$



- Solution : **skeleton-based implicit surfaces**

$f_i$  : decreasing function of  $d(P, S_i) \rightarrow$  *density of matter* around  $S_i$

**Skeletons :**  
points, curves  
surfaces...



- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

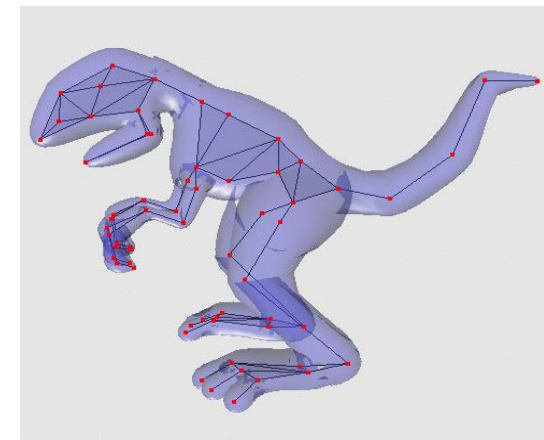
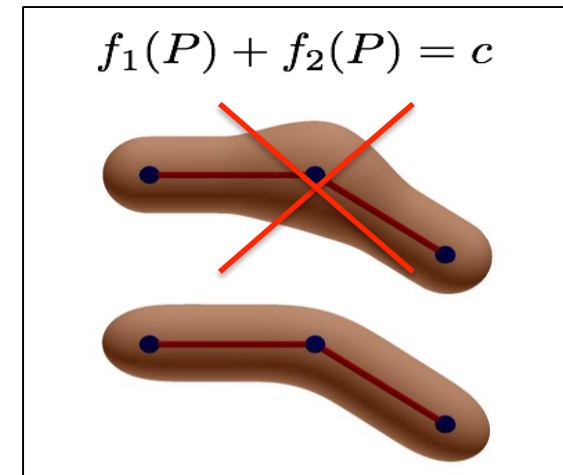
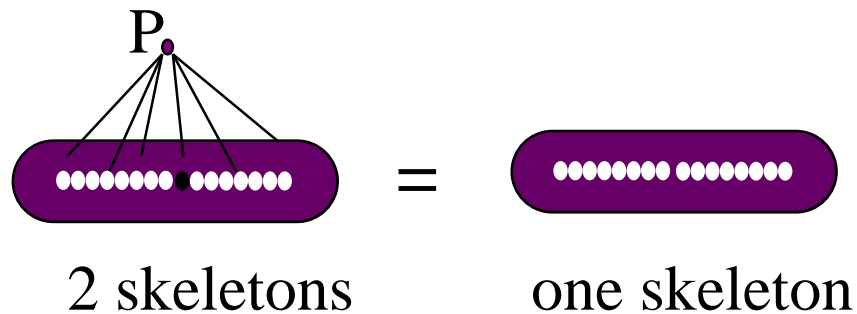
# *Skeleton-based implicit surfaces*

## *Convolution surfaces [Bloomethal 91]*

- Skeleton made of several segments  
Bulge at joints !

Convolution surface

$$f_i(P) = \int_S r(s) K(d(P, S)) ds$$

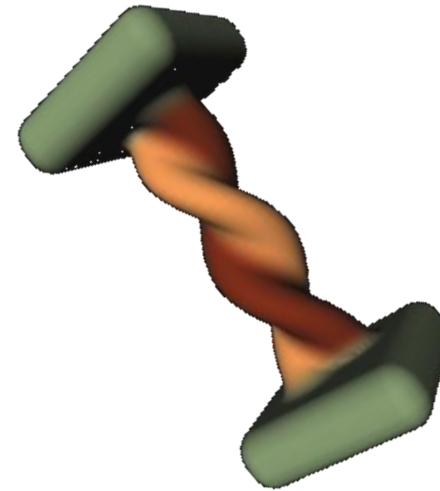


- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

# *Implicit surface Deform?*

- **Local deformation**

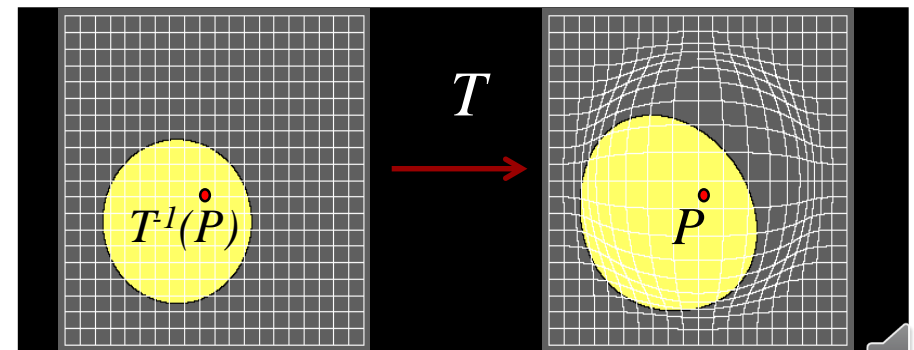
- Deform skeletons
- Edit thickness



- **Global deformation**

- Space deformation  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$

$$\hat{f}(P) = f(T^{-1}(P))$$



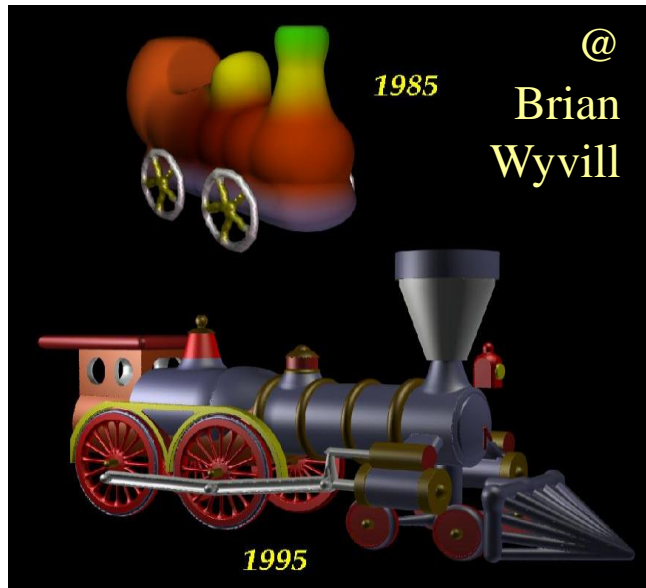
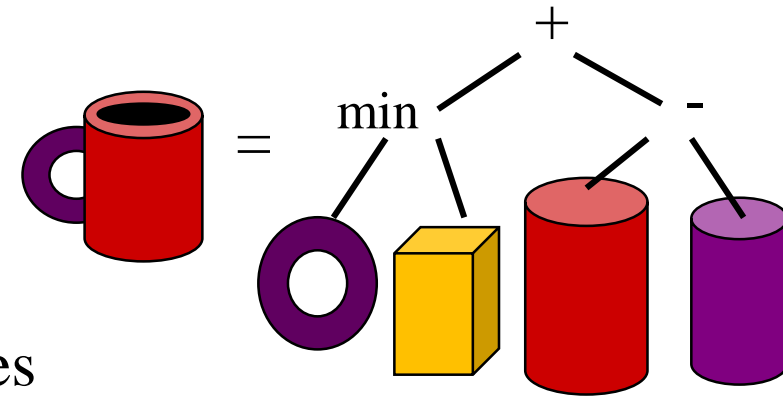
- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

## *Constructive implicit modeling*

### *Construction trees*

#### **‘BlobTrees’ extending CSG trees**

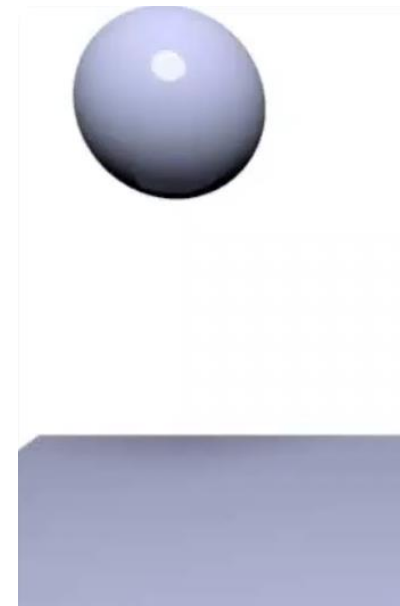
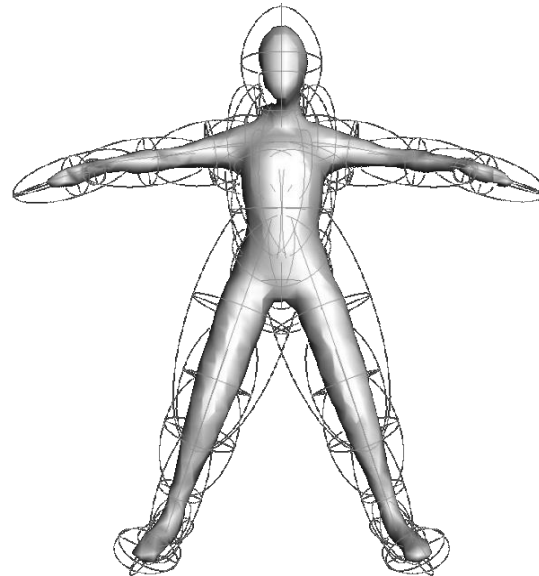
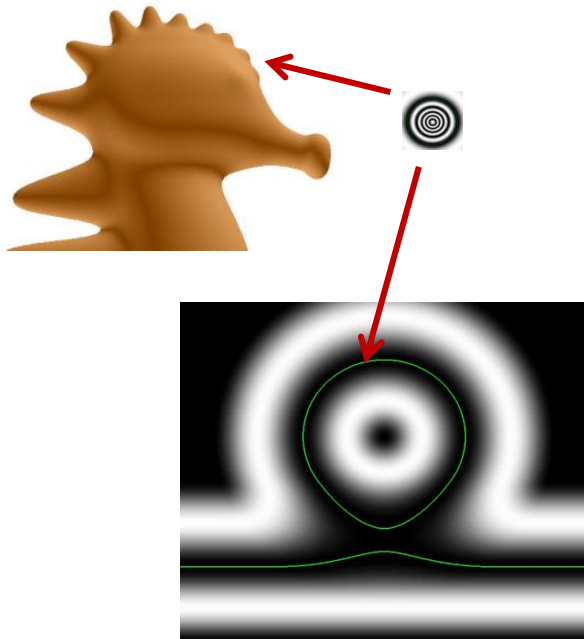
- Assembling nodes: +, -, max, min, ...
- Unary nodes for deformation
- Leaves = Skeleton-based implicit primitives



# *Recent research on implicit surfaces*

## **Challenging unsolved problems until 2010**

1. Small details vanish : “blobby” shapes
2. Non-local blends, that start at a distance  
→ *shapes and animations hard to control !*



- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

## *Problem 1*

### *Small details vanish*

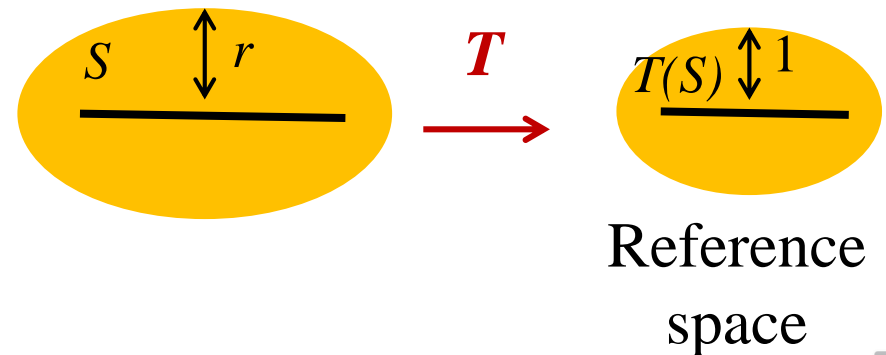
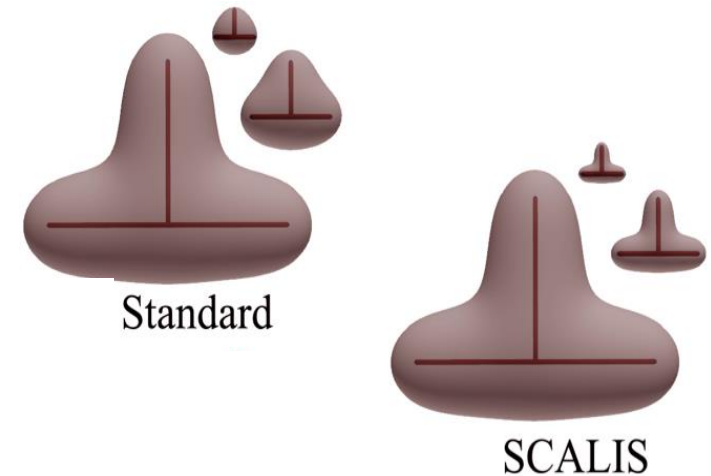
*Solution [Zanni 2013]*

**SCALIS** - normalized integral surface

- T: Scaling factor  $1/r$
- Normalized convolution

$$f_S(P) = \tilde{f}_{T(S)}(T(P))$$

Radius 1      Scaling



- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

# Problem 1

## Small details vanish

**General case : varying weight r!**

**SCALIS** [Zanni 2013]

*Convolution :*

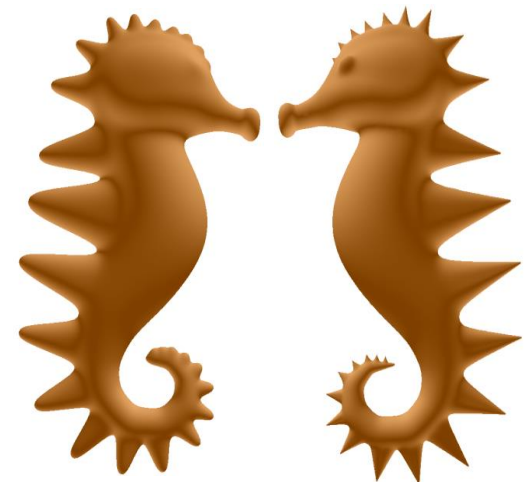
$$f_s(P) = \int_s r(s) K(d(P,S)) ds$$

$$f_s(P) = \frac{1}{N(K,c)} \int_s K\left(\frac{d(P,S)}{r(s)}\right) \frac{ds}{r(s)}$$

So that weight  
= radius

Scaling point

Scaling skeleton



Convolution

SCALIS



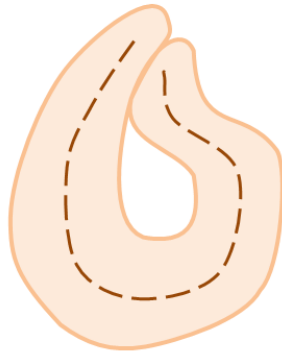
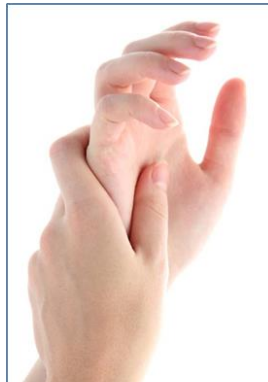


- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

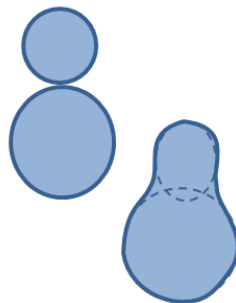
## *Problem 2*

*Which blending would we like?*

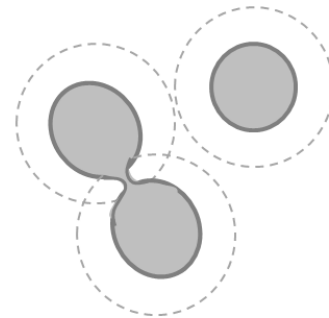
Skeletal



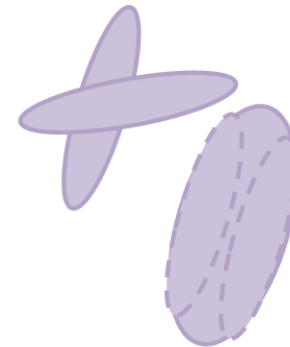
Upon contact



At distance



Orientation-based



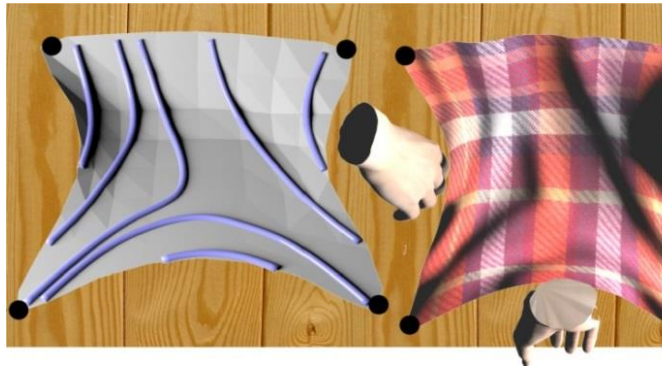
- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

## *Problem 2*

### *Blending at distance : Garment folds*

#### **If compression**

- Fold skeletons
- Implicit surfaces
- Deform cloth mesh



Input Simulation



[Rohmer 2010]

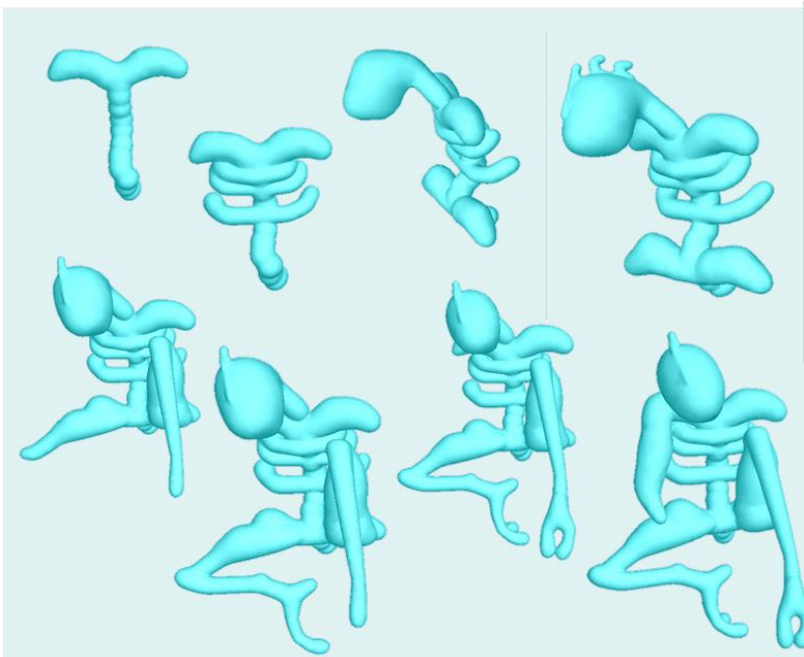


- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

## *Problem 2*

# *Blending upon contact*

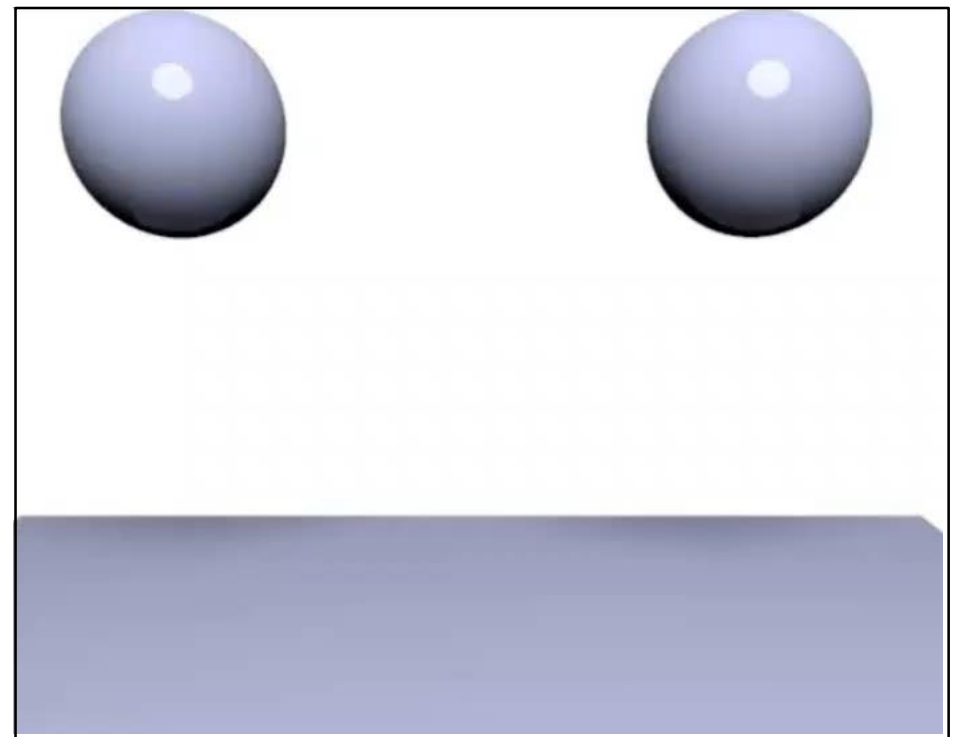
### **Constructive modeling**

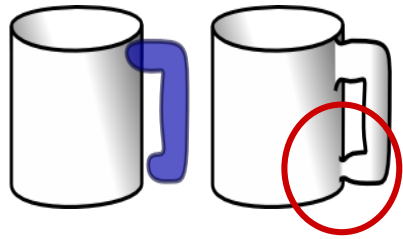


### **Animated water droplets**

Before

After





## *Solution: Gradient-based blends*

$f = f_1 + f_2$  blending at distance

**Idea:** blending should depend on

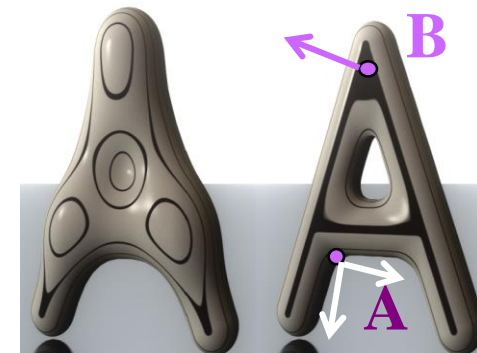
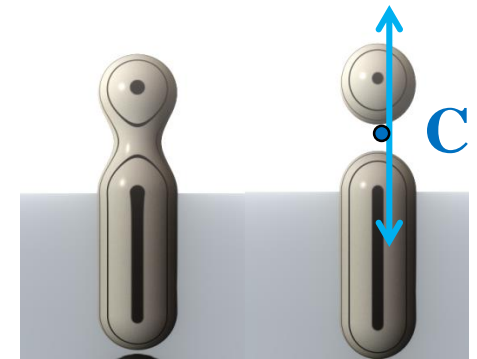
**field values *and* gradients**

**Desired behavior**

- Blend where **gradients are orthogonal**
- Union if **aligned** or **opposed**

**Method:**  $f = g(f_1, f_2, \nabla f_1, \nabla f_2)$

$g$  interpolates between union and blending



+ Gradient blend

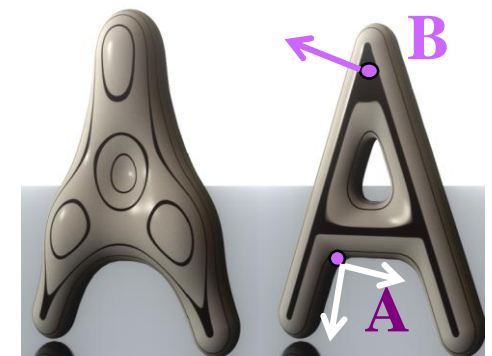
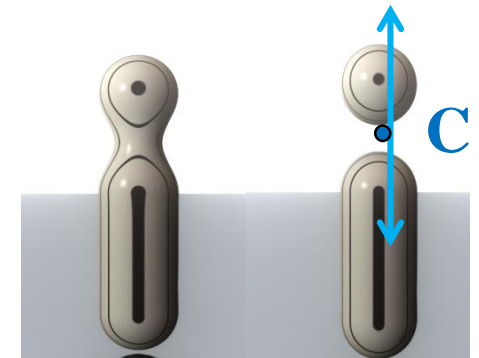
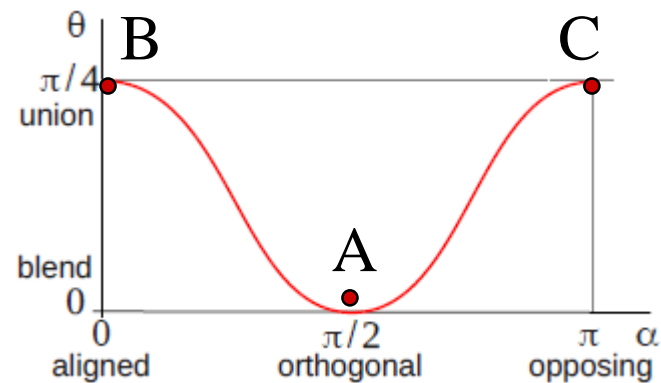
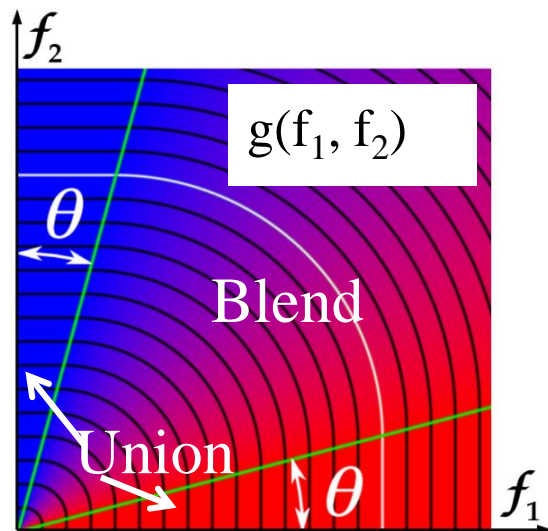


- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

## *Solution: Gradient-based blends*

**Solution** [Gourmel 2013]

- Blending operator with a blending angle  $\Theta$
- $\Theta$  function of angle between gradients



+

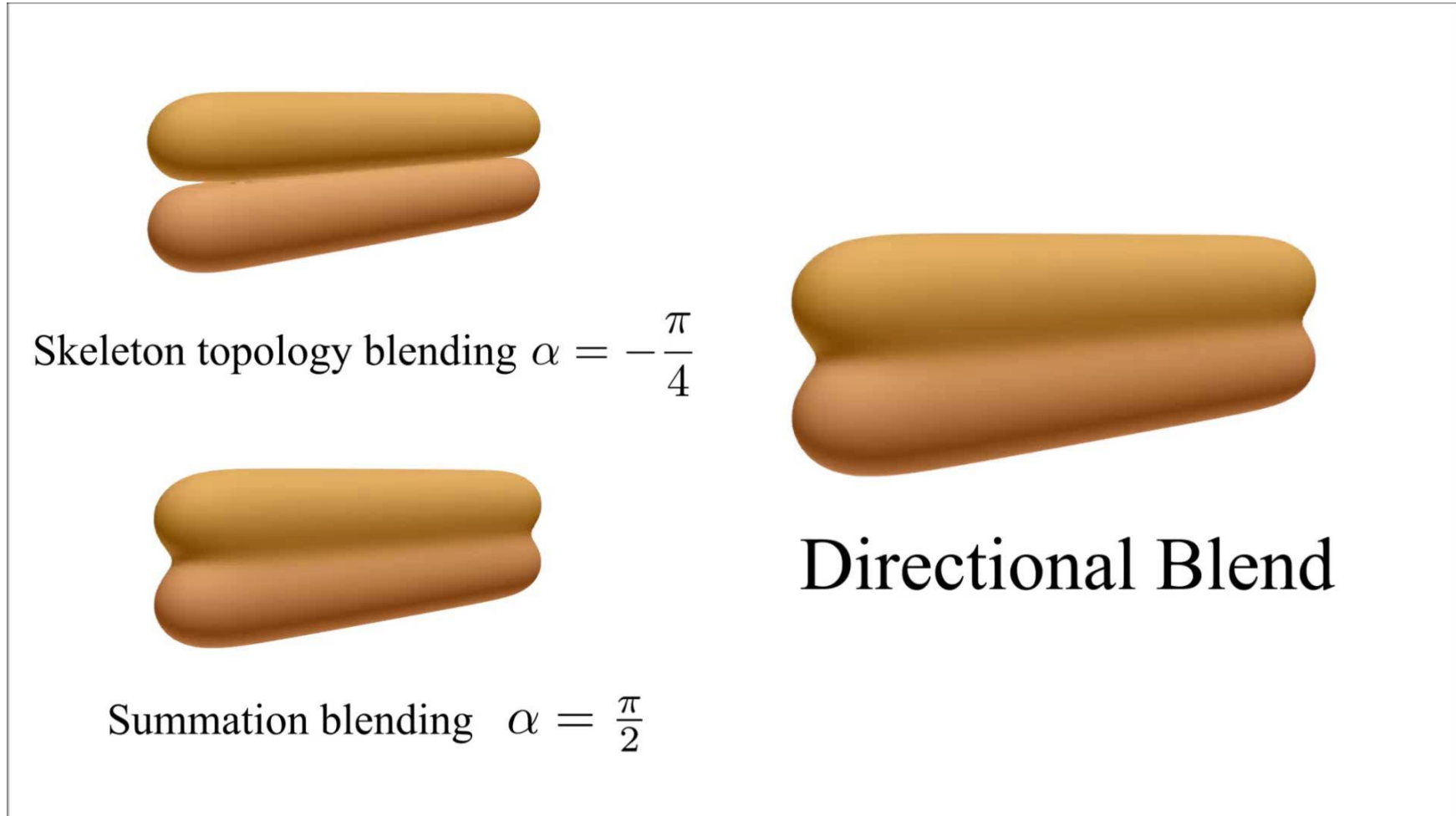
Gradient blend



- ✓ *Constructive modeling*
- ✓ *Choice of a representation*
- ✓ *Zoom : implicit surfaces*

# *Directional blending*

*[Zanni 2015]*



# *Separating shapes instead of assembly?*

**Implicit untangling [Buffet 2019]**

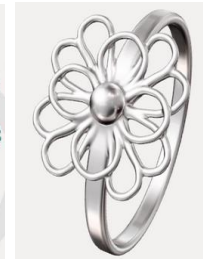
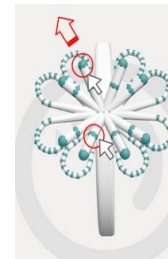




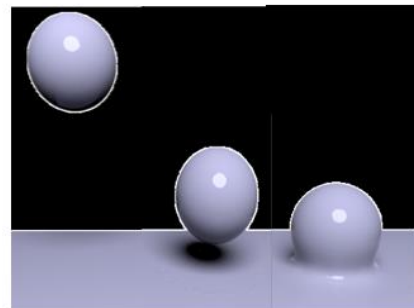
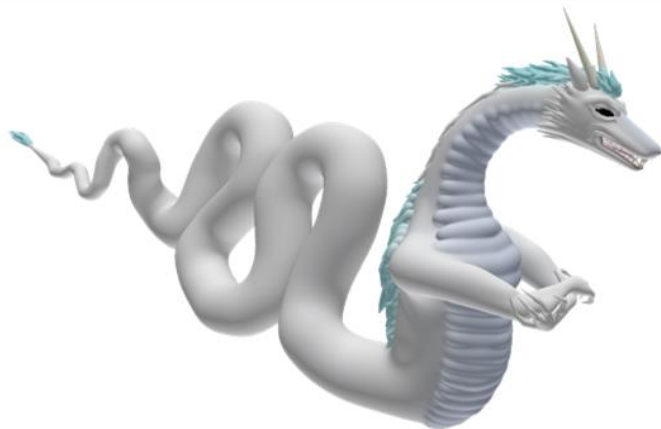
# Conclusion

## *Continuous shape representations for Constructive modeling*

- Spline surfaces good for 2D shapes
- 3D shapes easier with implicit surfaces
  - ✓ Intuitive control using skeletons
  - ✓ Precise blending control is mandatory



Jweel @Skimlab





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